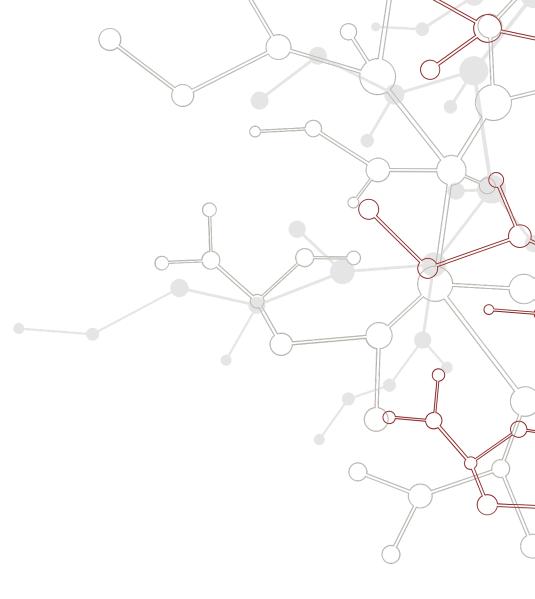
Physics Informed Foundation Models For Coherent Diffraction Imaging

Oliver Hoidn, Aashwin Mishra, Matt Seaberg, Apurva Mehta







Lensless imaging is compute-bound

Lensed Imaging: Real time feedback but lower resolution.

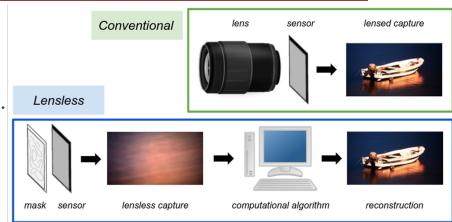
Lensless Imaging: Higher resolution but no real time feedback.

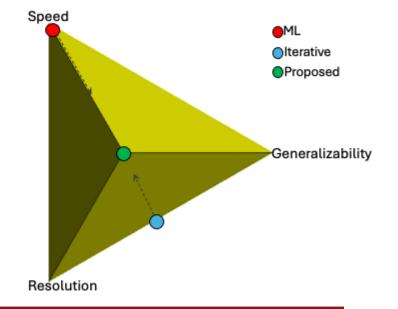
Proposed research: high resolution *and* real time feedback, & scaling with LCLS-II-HE.

Extant iterative approaches are too slow.

New ML approaches are fast, but unreliable & blurry reconstruction.

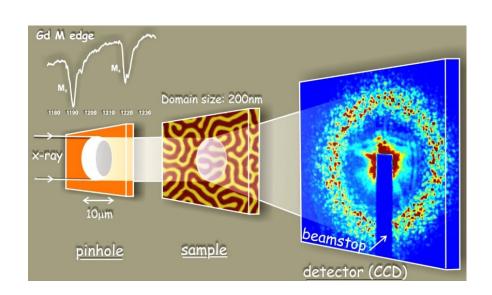
- Hybrid approach: ML speed & physics-based reliability.
 - a) Physics Informed: Robust & Generalizable,
 - b) Probabilistic: Reliability & Trust.
 - c) Physics based Resolution Maximization
 - d) Advanced architectures: data scaling & better reconstruction.

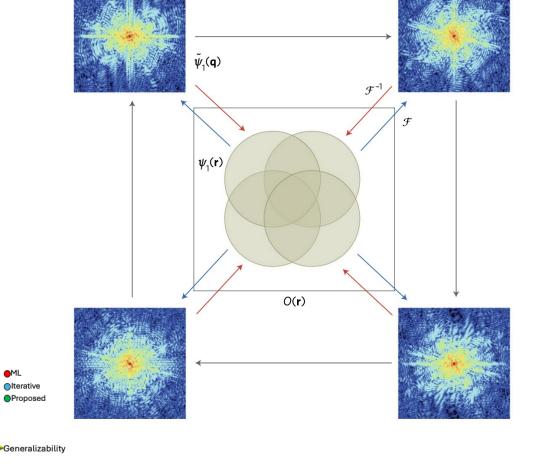




Physics+ML for High-Resolution, Real-Time, Reliable Imaging, scaling with LCLS-II-HE

Scanning Coherent Diffractive Imaging





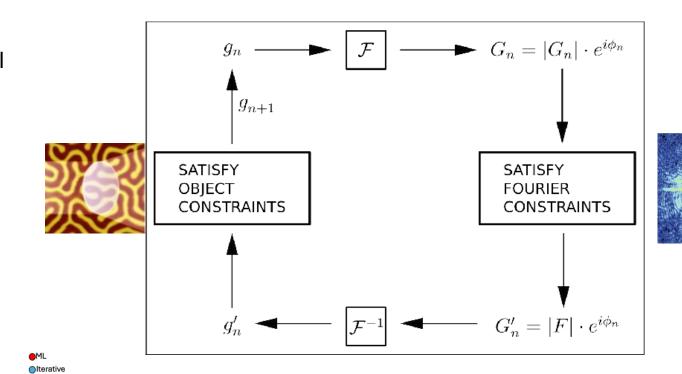


The challenge: iterative phase retrieval is slow

Proposed

Generalizability

- Reconstruction is constraint-driven:
 - Intensity-matching in reciprocal space
 - Real-space constraints (e.g. shrink-wrapping, overlaps)
- Necessarily iterative and slow



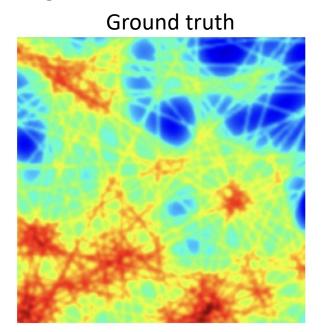


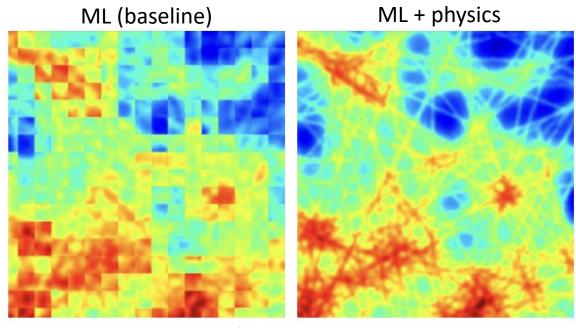
Physics-Informed Neural networks for generalizable reconstruction

Proof of concept: deep learning-based scanning coherent diffractive imaging with physicsinformed neural networks (PINNs) [1]

- Failure modes of prior, non-PINN deep learning approaches:

 - Inefficient training (i.e. poor generalization) Unphysical inverse problem solution → low resolution + artifacts
 - Demanding in infrastructure and (labeled) data





[1] Cherukara et al., doi.org/10.1063/5.0013065

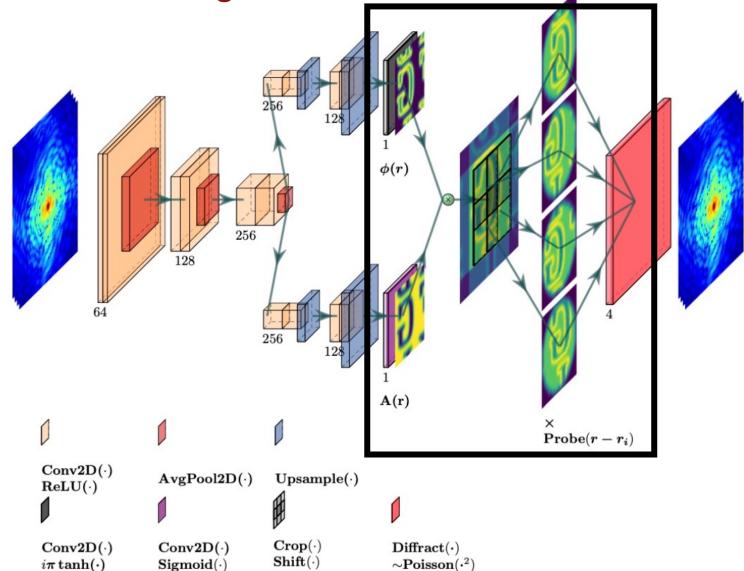
^[2] Hoidn et al., doi.org/10.1038/s41598-023-48351-7

Physics-Informed Neural networks for generalizable reconstruction

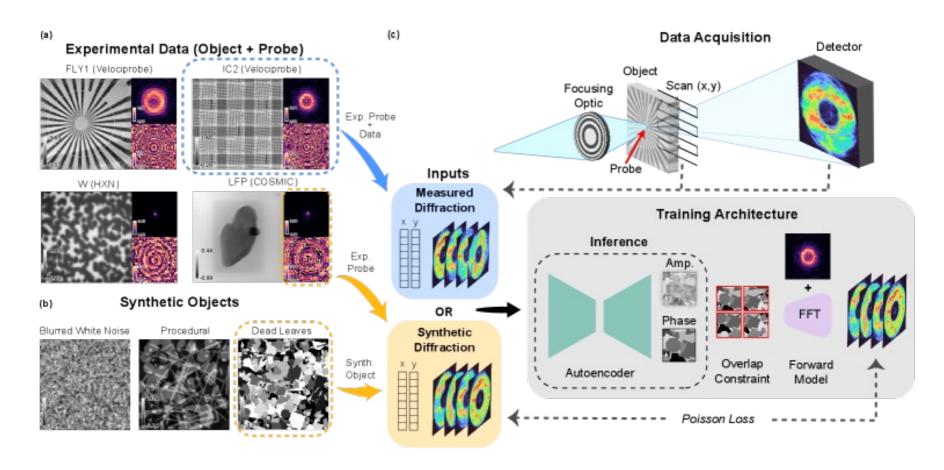
 Basic idea: incorporating diffraction physics as architectural constraints

Limitations:

- 128 x 128 max pixel dimensions → sacrifices qrange & resolution
- Modest model capacity
- Lack of interpretability and uncertainty quantification



Experimental results (APS)



[8] Vong et al. Npj Computational materials, in review

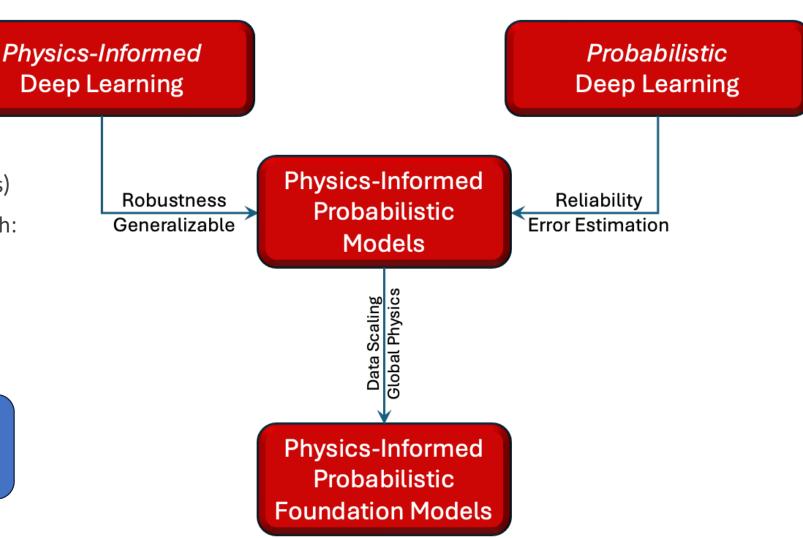


The path forward

Resolution and dose efficiency improvement through:

- Noise modeling
- Architectural scaling (e.g. SRGANs)
- Interpretability and generalization through:
 - Probabilistic machine learning
 - Vision transformer architectures

Physics-informed foundation models





Two paths forward

Scaling speed, resolution and generalization

Convolutional U-nets:

- Ultimate inference speed (100-1000x conventional algorithms) at the expense of generalization
- 'Easy' path to real-time reconstruction at 30,000 frames per second through parallel inferencetime scaling
- Very rapid training

Vision transformers

- Ultimate generalization and interpretability at the expense of high data and compute requirements
- Slow training but potential value as a foundation model for diffractive imaging

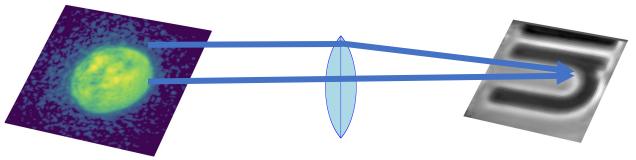


Physics-informed foundation models

Scaling approach: replace CNN backbone by vision transformer (ViT)

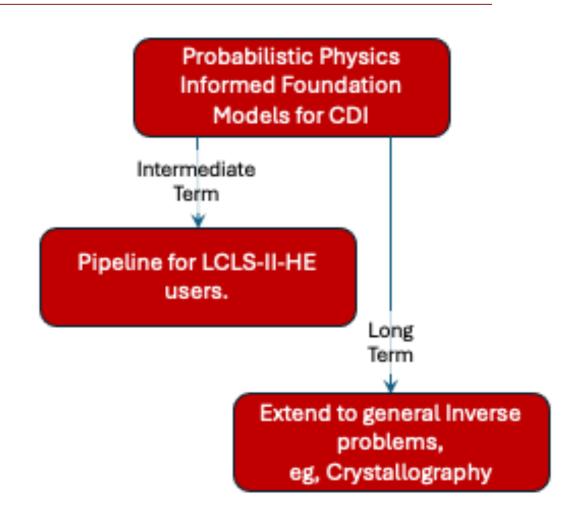
- Standard CNN architectures for computer vision:

 Local receptive fields → poor match to the Fourier transform properties that govern far-field diffraction
 - Limited model capacity → not generalizable enough to reconstruct truly diverse object morphologies
- Transformer architectures:
 - Global receptive fields by default
 - Superior generalization [7]
- ViT foundation models would also provide:
 - Interpretable latent space maps
 - Essential for model-driven experiment design
 - Transfer learning opportunities



Conclusions and beyond imaging

- Direct ramifications on other imaging techniques, eg crystallography.
- Beyond Imaging: Data compression via latent space embeddings,
 Active Learning for design of experiments, etc.
- Extend to Physics Informed Foundation Models for general Inverse problems at SLAC.
- Rapid feedback impact on nanoscale characterization capabilities for fields like heterogeneous materials.
 - This capability is being developed right now at SLAC and collaborating institutions (ANL, LBL)





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- [6] Gal, Y. and Ghahramani, Z., 2016, June. Dropout as a bayesian approximation: Representing model uncertainty in deep learning. In *international* conference on machine learning (pp. 1050-1059). PMLR.
- [7] He, K., Chen, X., Xie, S., Li, Y., Dollár, P. and Girshick, R., 2022. Masked autoencoders are scalable vision learners. In *Proceedings of the IEEE/CVF conference on computer vision and pattern recognition* (pp. 16000-16009).